

# Learning a Static Analyzer from Data



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# Writing a Static Analyzer



Framework for Java  
Pointer Analysis



17 contributors



Static Type Checker  
for JavaScript



Static Type Checker  
for JavaScript



~400 contributors

Writing static analyzer is



Writing static analyzer is **hard**

Writing static analyzer is **frustrating**

Writing static analyzer is **time consuming**

Writing static analyzer is **brittle**

[Learn more](#)

# Example of Unsound Analysis



flow



v0.51.0 ▼

```
1 /* @flow */
2
3 var data = [7, 2, 9];
4
5 function collect(val, idx, obj) {
6   if (val > this.threshold) { Missed Error
7
8   }
9 }
10
11 data.threshold;      Error correctly reported
12 data.forEach(collect);
```

Errors

JSON

AST

11: data.threshold;

^ property `threshold`. Property not found in

11: data.threshold;

^ Array

*Can we learn a static analyzer?  
(aka its abstract transformers)*

# This Work: Learn Static Analyzer from Data

*Input Dataset*

$$\mathcal{D} = \{\langle x^j, y^j \rangle\}_{j=1}$$

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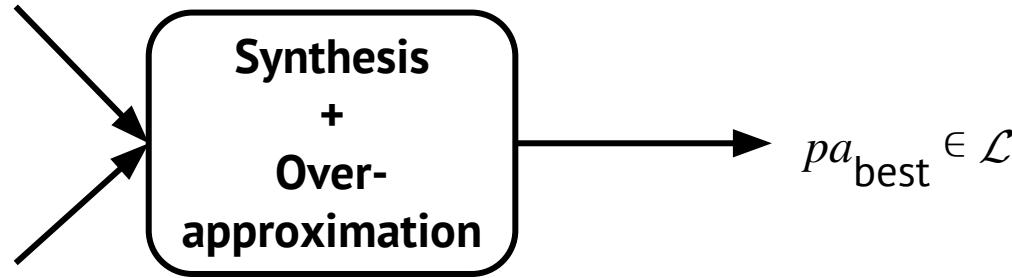
*Language  $\mathcal{L}$   
for abstract  
transformers*

# This Work: Learn Static Analyzer from Data

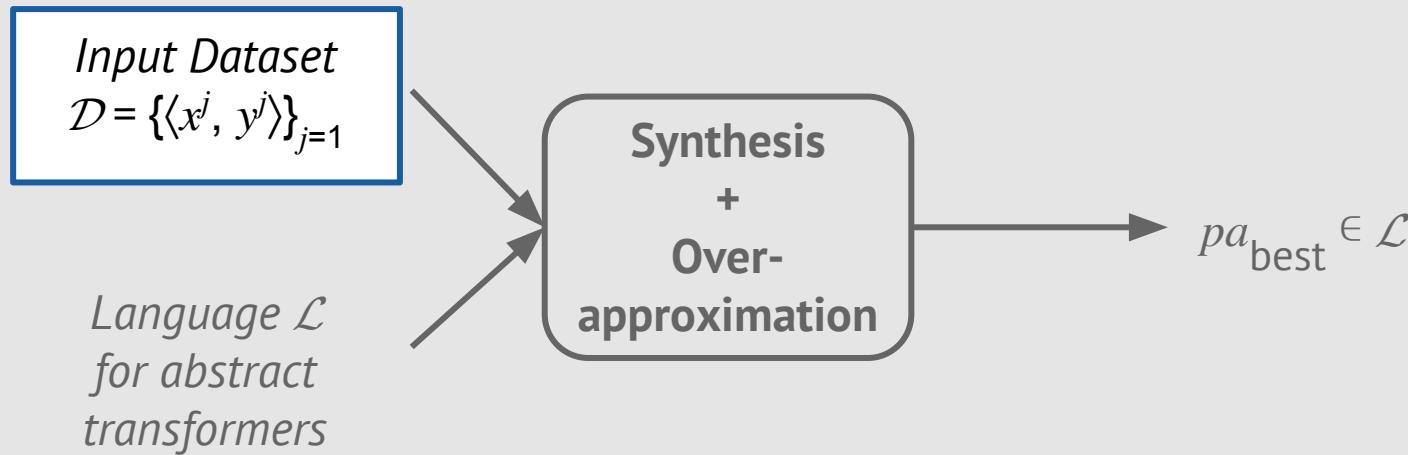
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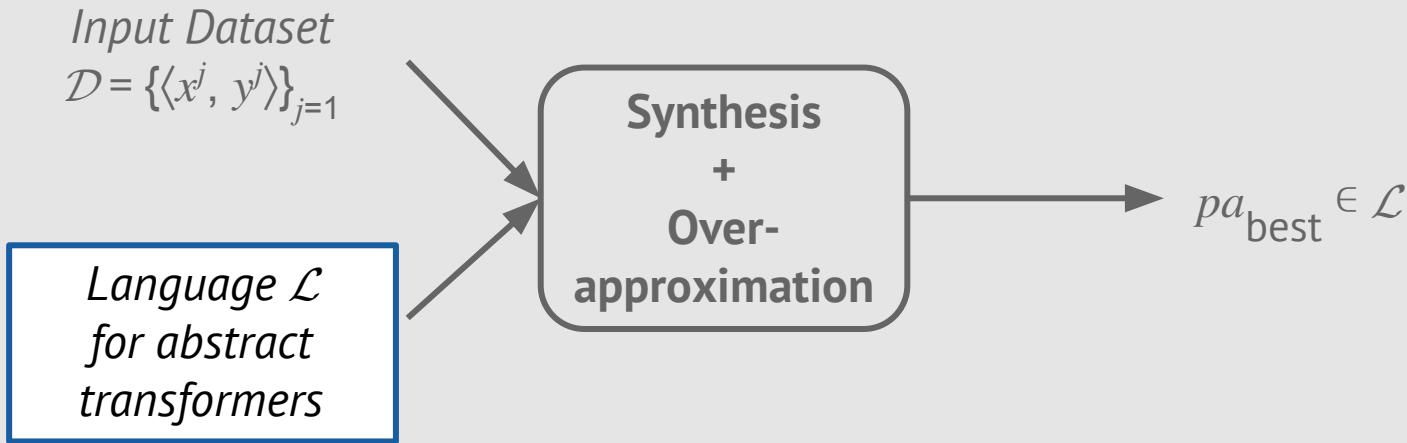


# This Work: Learn Static Analyzer from Data



How to obtain suitable dataset?

# This Work: Learn Static Analyzer from Data

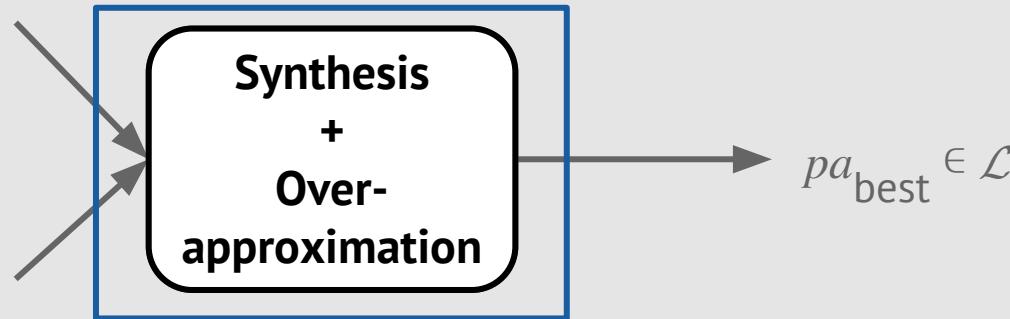


What is the language over which to learn?  
How to allow generating new interesting transformers?

# This Work: Learn Static Analyzer from Data

*Input Dataset*  
 $\mathcal{D} = \{\langle x^j, y^j \rangle\}_{j=1}^n$

*Language  $\mathcal{L}$  for abstract  
transformers*



**How to design scalable learning over large search spaces?  
How to prevent overfitting?**

*Can we learn a static analyzer?*

*interpretable and sound*

↓  
*Can we learn a static analyzer?*

## Problem Formulation

$$pa_{\text{best}} = \arg \min_{pa \in \mathcal{L}} cost(\mathcal{D}, pa) \quad \leftarrow \begin{array}{l} \text{analysis} \\ \text{precision} \end{array}$$

**analysis  
soundness** → st.  $\forall \langle x, y \rangle \in \mathcal{D} . \alpha(y) \sqsubseteq pa(x)$

# An Example Transformer Learned

```
Array.prototype.filter ::=  
  if caller has one argument then  
    points-to global object  
  else if 2nd argument is Identifier then  
    if 2nd argument is undefined then  
      points-to global object  
    else  
      points-to 2nd argument  
  else if 2nd argument is this then  
    points-to 2nd argument  
  else if 2nd argument is null then  
    points-to global object  
  else //2nd argument is a primitive value  
    points-to new allocation site
```

# An Example Transformer Learned

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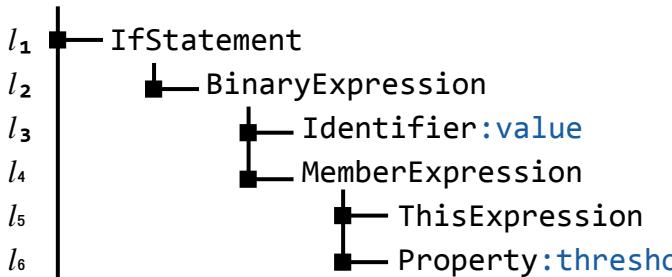
*Let us show the learning on an example analysis  
(aka points-to analysis)*

# Dataset: Points-to Analysis

## Program

```
function collect(value, idx, obj) {  
    if (value >= this.threshold) {  
        ...  
    }  
    ...  
}
```

## Abstract Syntax Tree (AST)



*execution  
reads/writes*

-

-

$o_1$

-

$o_2$

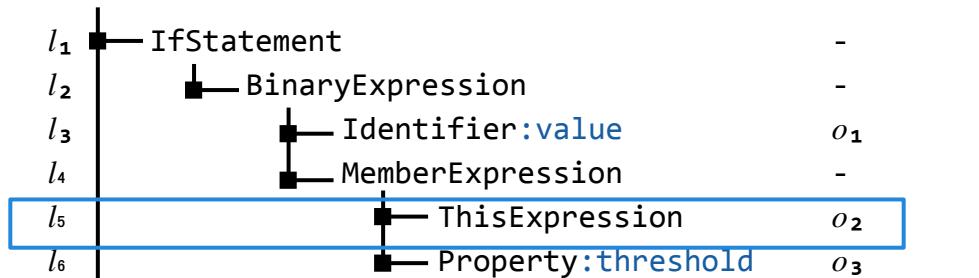
$o_3$

# Dataset: Points-to Analysis

## Program

```
function collect(value, idx, obj) {  
    if (value >= this.threshold) {  
        ...  
    }  
    ...  
}
```

## Abstract Syntax Tree (AST)



$$\langle (AST, l_5), o_2 \rangle$$

$$\mathcal{D} = \{\langle \overset{\uparrow}{x^j}, \overset{\uparrow}{y^j} \rangle\}_{j=1}^n$$

# Language Describing Abstract Transformers

$$l \in \mathcal{L} := a \mid \text{if } g \text{ then } l \text{ else } l$$

$a \in \text{Actions}$        $g \in \text{Guards}$

```
function collect(val, idx, obj) {  
    if (val >= this.threshold) { ... }  
}  
  
var dat = [5, 3, 9];  
dat.filter( collect, ctx );
```

method name                  has  
is filter                  2nd argument  
 $g_1$                            $g_2$

Points-to Query

$a_1$

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method name  
is filter

$g_1$

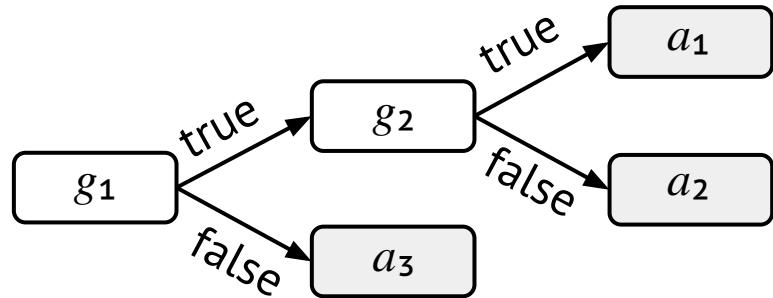
Points-to Query

$a_1$

$g_2$

2nd argument

$g_2$



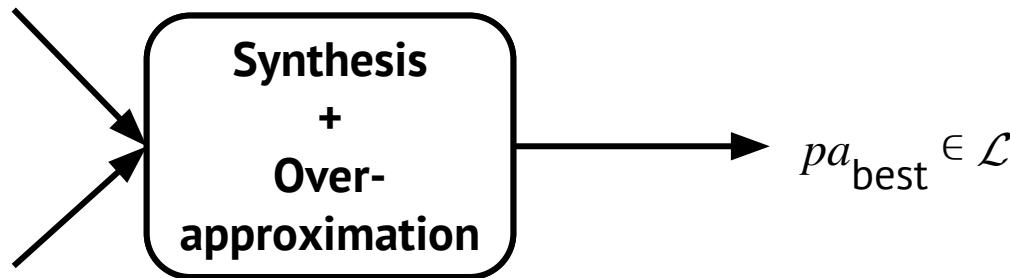
can be represented as decision tree

paths interpreted as abstract transformers

# Learning: Decision Trees

*Input Dataset*  
 $\mathcal{D} = \{\langle x^j, y^j \rangle\}_{j=1}$

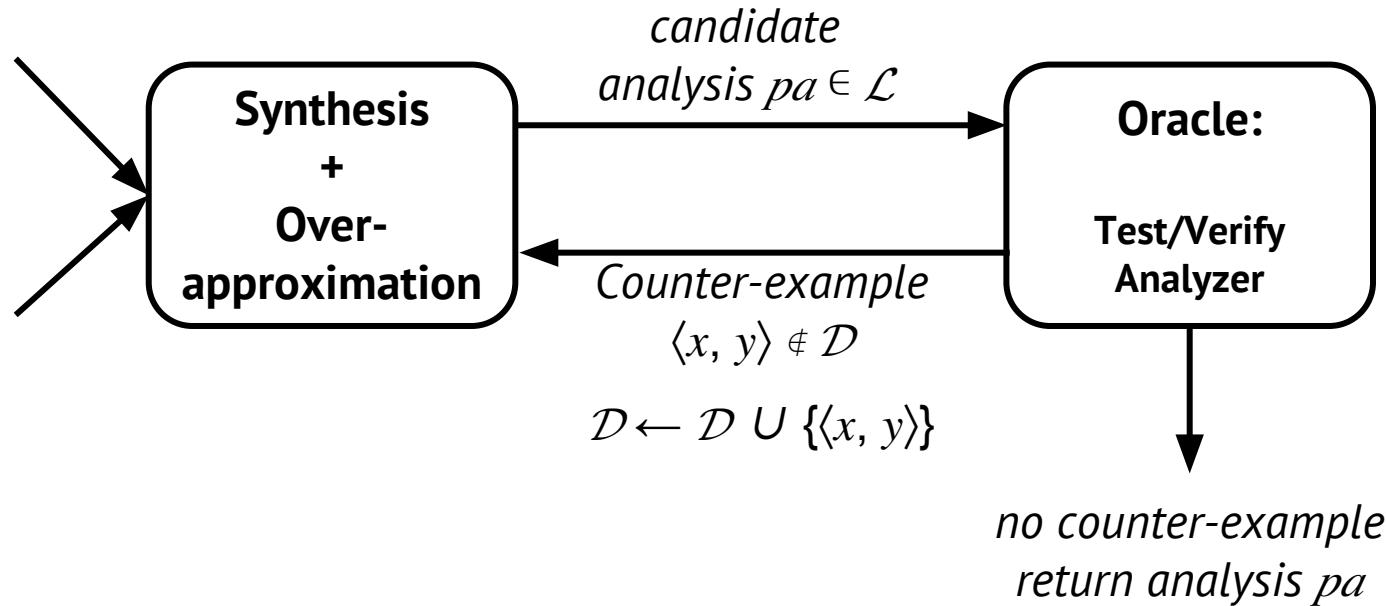
*Language  $\mathcal{L}$   
for abstract  
transformers*



# Learning: Decision Trees + CEGIS

*Input Dataset*  
 $\mathcal{D} = \{\langle x^j, y^j \rangle\}_{j=1}$

*Language  $\mathcal{L}$  for abstract  
transformers*



# Learning: Problem Formulation

## Problem Formulation

$$pa_{\text{best}} = \arg \min_{pa \in \mathcal{L}} cost(\mathcal{D}, pa)$$

st.  $\forall \langle x, y \rangle \in \mathcal{D} . \alpha(y) \sqsubseteq pa(x)$

guarantees analysis soundness

## Cost Function

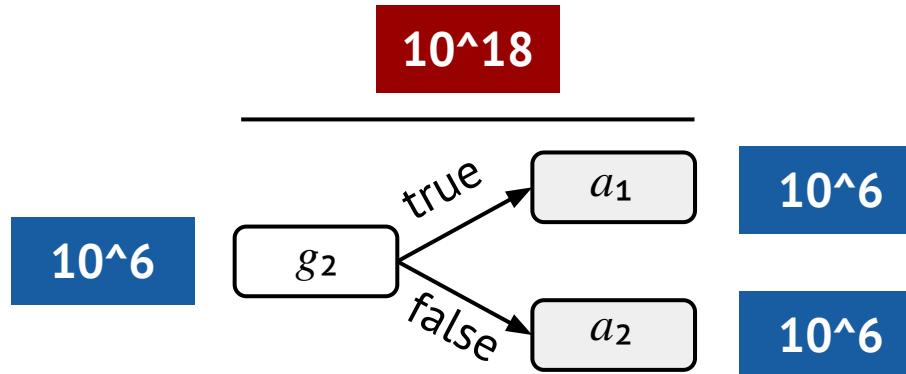
$$r(x, y, pa) = \mathbf{if} (y \neq pa(x)) \mathbf{then} 1 \mathbf{else} 0$$

$$cost(\mathcal{D}, pa) = \sum_{\langle x, y \rangle \in \mathcal{D}} r(x, y, pa)$$

prefer analysis with fewer errors

# Learning Algorithm

$l \in \mathcal{L} := a \mid \text{if } g \text{ then } l \text{ else } l$



Untractable

# Learning Algorithm

$$l \in \mathcal{L} := a \mid \text{if } g \text{ then } l \text{ else } l$$

**Key Idea: Synthesise Programs in Parts**

$10^6$

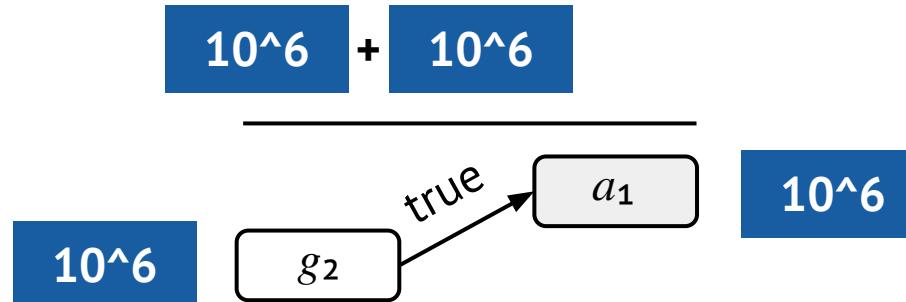
$a_1$

$10^6$

# Learning Algorithm

$$l \in \mathcal{L} := a \mid \text{if } g \text{ then } l \text{ else } l$$

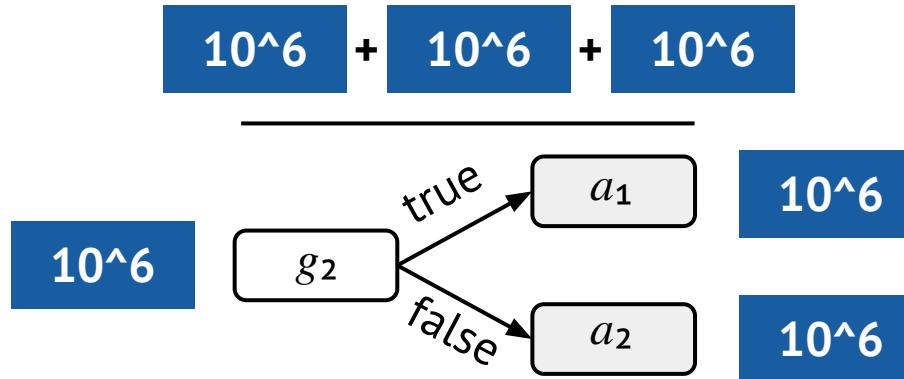
**Key Idea: Synthesise Programs in Parts**



# Learning Algorithm

$$l \in \mathcal{L} := a \mid \text{if } g \text{ then } l \text{ else } l$$

**Key Idea: Synthesise Programs in Parts**



# Learning Algorithm

$$a_{\text{best}} = \arg \min_{a \in \text{Actions}} \text{cost}(\mathcal{D}, a)$$

$$\text{cost}(\mathcal{D}, a_{\text{best}}) > 0$$



$a_{\text{best}}$

refine analysis

$\mathcal{D}$

$$\text{cost}(\mathcal{D}, a_{\text{best}}) = 0$$



$a_{\text{best}}$

no errors  
return  $a_{\text{best}}$

$\mathcal{D}$

# Learning Algorithm

$$g_{\text{best}} = \arg \max_{g \in \text{Guards}} \text{InfGain}(\mathcal{D}, g, a_{\text{best}})$$

$$\text{cost}(\mathcal{D}, a_{\text{best}}) > 0$$

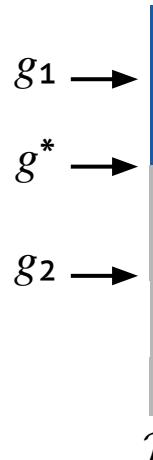
refine analysis



$a_{\text{best}}$

**Find split  
that separates**

$a_{\text{best}}$



$g_1 \rightarrow$

$g^* \rightarrow$

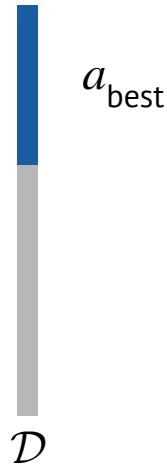
$g_2 \rightarrow$

# Learning Algorithm

$$g_{\text{best}} = \arg \max_{g \in \text{Guards}} \text{InfGain}(\mathcal{D}, g, a_{\text{best}})$$

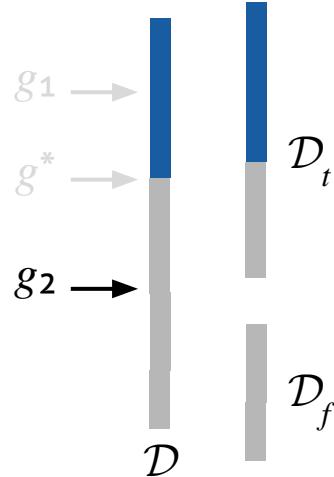
$$\text{cost}(\mathcal{D}, a_{\text{best}}) > 0$$

refine analysis



**Find split  
that separates**

$a_{\text{best}}$



$g_1 \rightarrow$

$g^* \rightarrow$

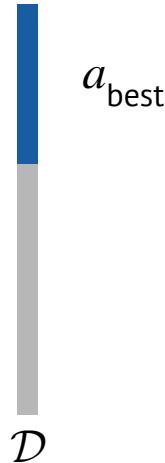
$g_2 \rightarrow$

# Learning Algorithm

$$g_{\text{best}} = \arg \max_{g \in \text{Guards}} \text{InfGain}(\mathcal{D}, g, a_{\text{best}})$$

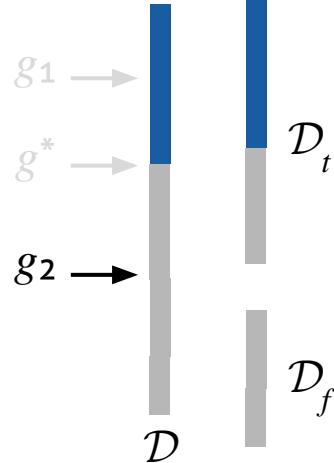
$$\text{cost}(\mathcal{D}, a_{\text{best}}) > 0$$

refine analysis



**Find split  
that separates**

$$a_{\text{best}}$$



$\text{InfGain}(\mathcal{D}, g, a_{\text{best}}) = 0$   
**no split reduces entropy**

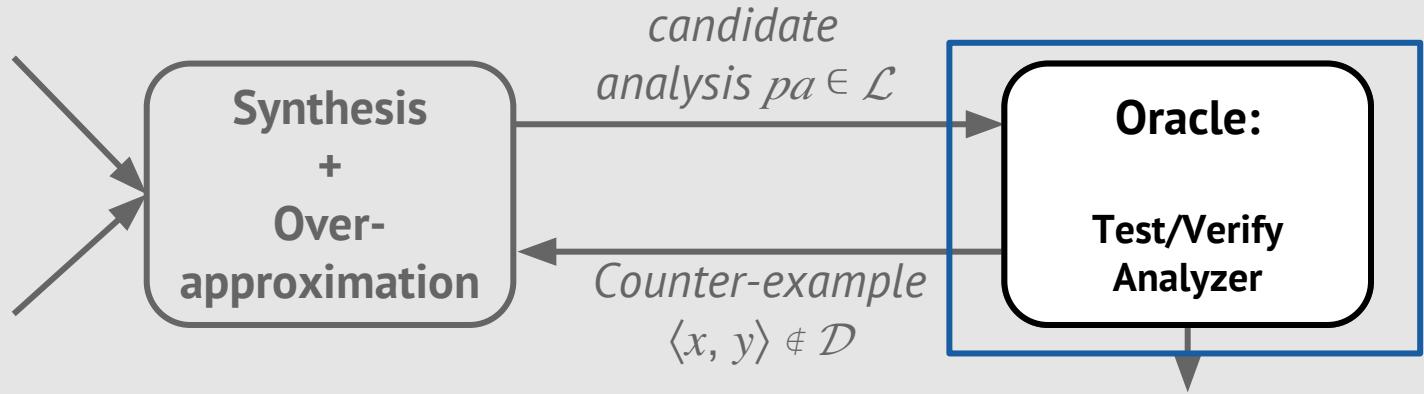


$\text{approximate}(\mathcal{D})$

# Learning: Decision Trees + CEGIS

*Input Dataset*  
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*Language  $\mathcal{L}$  for abstract  
transformers*



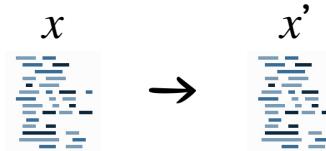
How to find complex counter-examples quickly?  
How to efficiently explore hard to find corner cases?

# Naive Approach: Random Fuzzing

1. Pick a random training example

$$\langle x, y \rangle \in \mathcal{D}$$

2. Mutate the input randomly



3. Obtain the correct label

Execute  $x' \rightarrow \mathcal{D}'$

4. Check for correctness

$$\forall \langle x, y \rangle \in \mathcal{D}' . \alpha(y) \sqsubseteq pa(x)$$

5. Repeat

# Naive Approach: Random Fuzzing

1. Pick a random training example
2. Mutate the input randomly
3. Obtain the correct label
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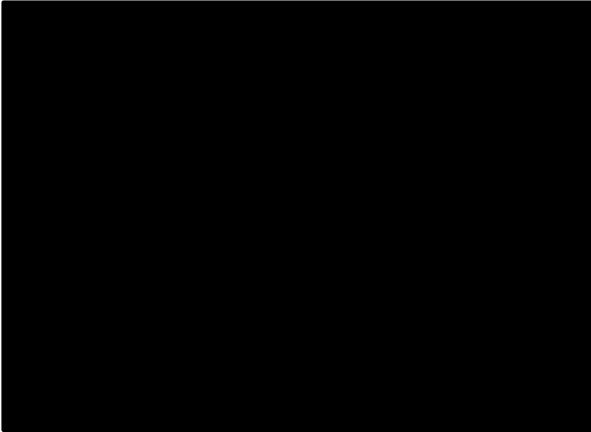
Exponential Number  
of Choices

Slow

When to stop?

# The Oracle: Testing an Analyzer

**Key Idea:** Take advantage of candidate analysis  $pa$

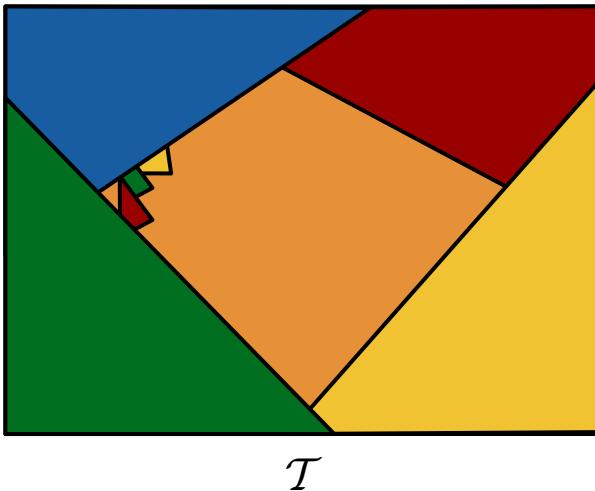


How to sample from  
space of all programs?

$\mathcal{T}$

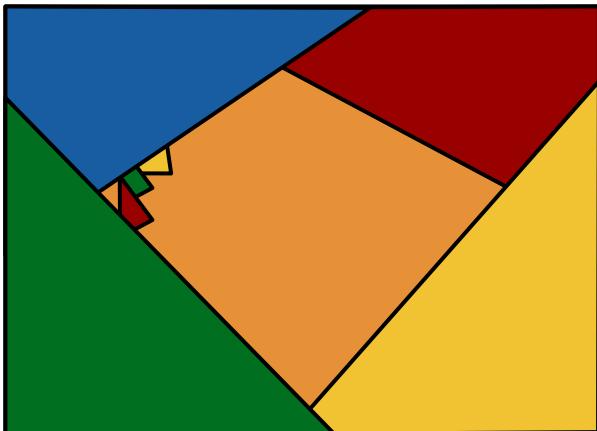
# The Oracle: Testing an Analyzer

**execution path  
coverage of  $pa$**



# The Oracle: Testing an Analyzer

execution path  
coverage of  $pa$

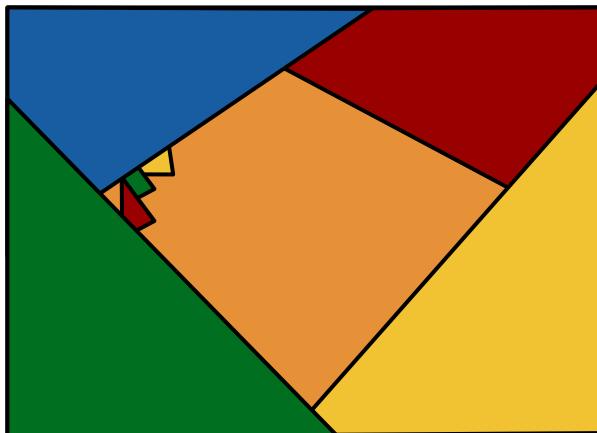


mutate only parts  
that affect  $pa$

```
fnc collect(val, idx, obj) {  
    if (val >= this.threshold){  
        ...  
        Query  
    }  
}  
}  
Locations accessed by  
the analysis  
var dat = [5, 3, 9];  
dat.filter(collect, ctx);
```

# The Oracle: Testing an Analyzer

execution path  
coverage of  $pa$



mutate only parts  
that affect  $pa$

```
fnc collect(val, idx, obj) {  
    if (val >= this.threshold){  
        ...  
    }  
}  
} Locations accessed by  
the analysis  
var dat = [5, 3, 9];  
dat.filter(collect, ctx);
```

select relevant  
program mutations

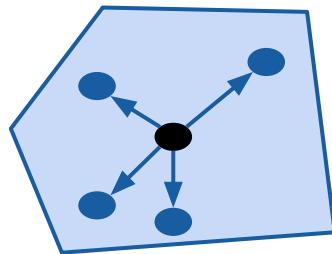
Modification via  
Equivalence Modulo  
Abstraction (EMA)

Modification via  
Global Jumps

# The Oracle: Testing an Analyzer

## Modifications via Equivalence Modulo Abstraction (EMA)

*Semantic preserving mutations*



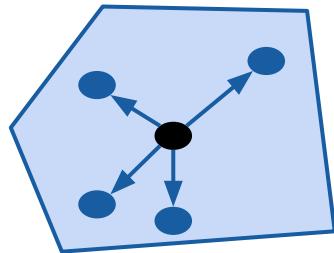
Adding dead code  
Renaming variables  
Renaming user defined functions  
Side-effect free expressions

$\mathcal{T}$

# The Oracle: Testing an Analyzer

## Modifications via Equivalence Modulo Abstraction (EMA)

*Semantic preserving mutations*



Adding dead code  
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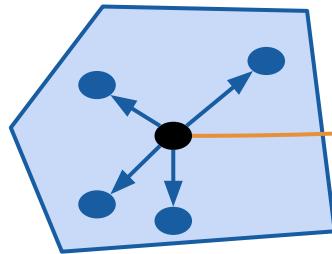
labels  $y$   
can be reused

$\mathcal{T}$

# The Oracle: Testing an Analyzer

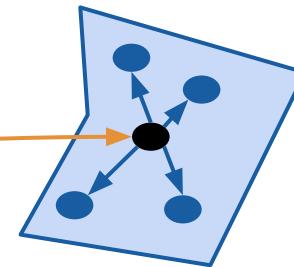
**Modifications via  
Equivalence Modulo  
Abstraction (EMA)**

*Semantic preserving mutations*



*Non-semantic preserving mutation*

**Modifications via  
Global Jumps**



$\mathcal{T}$

# Evaluation

*ECMAScript (ECMA-262) Conformance Suite*

**15 675**

Programs



## Points-to Analysis

```
function collect(val, idx, obj) {  
    if (val >= this.threshold) { ... }  
}  
  
var dat = [5, 3, 9];  
dat.filter( collect, ctx );
```

## Allocation Site Analysis

```
var obj = {a: 7};  
var arr = [1, 2, 3, 4];  
if (arr.slice(0, 2) == ... )  
var n = new Number(7);  
var obj2 = new Object(obj);  
try { ... } catch (err) { ... }
```

# Approach Instantiation for Points-to Analysis

*Input Dataset*  
 $\mathcal{D} = \{\langle x^j, y^j \rangle\}_{j=1}$

$y \leftarrow \text{concrete object id}$

*Language  $\mathcal{L}$   
for abstract  
transformers*

$a \in \text{Actions} ::= \varepsilon \mid \text{Move}; a$   
 $\text{Move}_{\text{Core}} ::= \text{Up}, \text{Left}, \text{Right},$   
 $\quad \text{DownFirst}, \text{DownLast}, \text{Top}$   
 $g \in \text{Guards} ::= \varepsilon \mid \text{Move}; g \mid \text{Write}; g$   
 $\text{WriteOp} ::= \text{WriteValue}, \text{WriteType}, \text{WritePos},$   
 $\quad \text{HasLeftSibling}, \text{HasRightSibling}, \text{HasChild}$

*Synthesis*

$(\mathcal{H}, \sqsubseteq), \alpha, \gamma$

**semantic preserving mutations    non-semantic preserving mutations**

*Oracle*

Adding dead code  
Renaming variables  
Renaming user defined functions  
Side-effect free expressions

Add method arguments  
Add method parameters  
Change program constants



*rules missed by  
Facebook Flow*

# Learned Points-to Analysis

<i>Function Name</i>	<i>Dataset Size</i>	<i>Analysis Size</i>	<i>Counter-examples Found</i>
<b>Function.prototype</b>			
call()	26	97(18)	372
apply()	6	54(10)	182
<b>Array.prototype</b>			
map()	315	36(6)	64
some()	229	36(6)	82
forEach()	604	35(5)	177
every()	338	36(6)	31
filter()	408	38(6)	76
find()	53	36(6)	73
findIndex()	51	28(7)	96
<b>Array</b>			
from()	32	57(7)	160
<b>JSON</b>			
stringify()	18	9(2)	55

**Average Learning Time 14 minutes (4 min synthesis, 10 min oracle)**

# Learned Allocation Site Analysis

**134 721**

training dataset size

**905**

counter-examples found

**99**

refinement iterations

**3 hours**

Synthesis time

**7 hours**

time to find counter-examples

## Overview of Learned Analysis

```
if HasPrevNodeValue then ⊤  
elif WriteType == CallExpression then  
    if Up WriteType == ExpressionStatement then  
        ⊤          // return value not assigned  
    else ...  
elif WriteType == ArrayAccess then ...  
elif WriteType == ObjectExp|ArrayExp|RegExp then  
    NewAlloc // implicit constructors  
elif WriteType == NewExpression then  
    ...      // explicit constructor  
elif Up WriteType == AssignmentExpression  
    if left hand side of the assignment then NoAlloc  
    ...
```

# Learning a Static Analyzer from Data

Learns practical abstract transformers  
missed by existing state-of-the-art analyzers

*Input Dataset*

$$\mathcal{D} = \{\langle x^j, y^j \rangle\}_{j=1}^n$$

*Language  $\mathcal{L}$  for abstract  
transformers*

